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On Cyclic Dependencies and Regulators in Time-Sensitive Networks

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April 30th, 2020

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Introduction

In time-sensitive networks, delays at network elements have to be bounded in worst case, not in average.

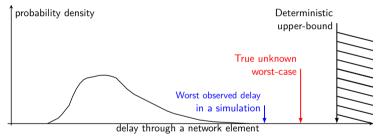


Figure: Distribution of suffered delay through a network element

• Upper-bounding is challenging when we have **cyclic dependencies**.

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What is a cyclic dependency ?

When directed path of flows form a cycle.

= When the **directed graph** of **contention points** has a cycle.

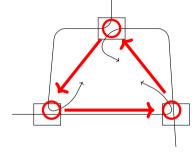


Figure: A cyclic dependency

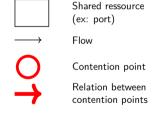
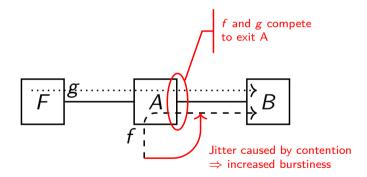


Figure: Legend

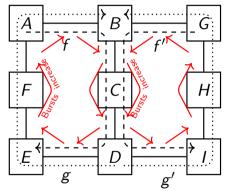
Why are cyclic dependencies an issue ?

■ In class-based asynchronous networks (FIFO-per-class policy).



Why are cyclic dependencies an issue ?

■ In **class-based** asynchronous networks (FIFO-per-class policy).



For some networks, cascade of **always increasing** bursts:

[Andrews, 2009]:

For any $\epsilon > 0$, there exists a network with FIFO scheduling and load ϵ that is unstable (= unbounded bursts, unbounded latencies)

Figure: Cascades of burst increase

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For any network with cyclic dependencies:

Guarantee worst-case delays.

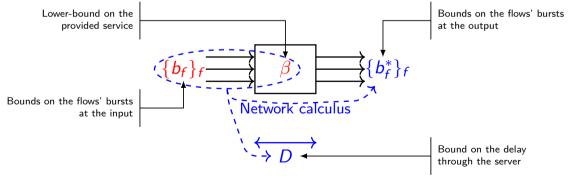
- Minimize deployment cost of the network.
- Keep high-scalability architectures.

Network Calculus

Can be used:

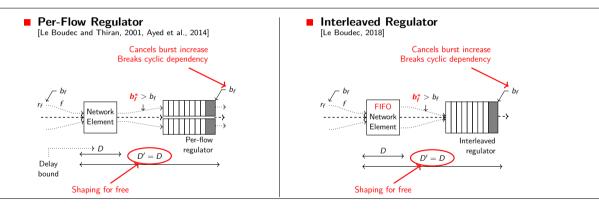
- to compute **delay bounds**.
- to provide sufficient conditions for the stability of networks with cyclic dependencies.

Inputs, transfer function and outputs.



Traffic re-shaping breaks burst cascade

Reshaping in the network using traffic regulators.



■ Radical solution: **reshape at every node** ⇒ bursts never increase.

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Contributions

E Reshape only on a subset of nodes \rightarrow partial deployment.

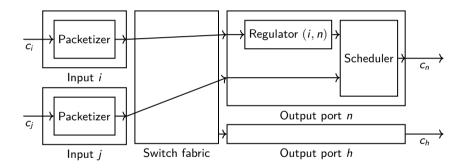
- Performances compared to full deployment at every node ?
- How to select the positions ?

Low-Cost Acyclic Network (LCAN): { removes all cyclic dependencies with minimum regulators

Performances of full and partial deployment vs no deployment at all ?

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Network model



Content

1 Low-Cost Acyclic Network (LCAN)

- Modeling the effect of regulators on cyclic dependencies
- Obtaining minimum positions

2 Fixed-Point Total Flow Analysis (FP-TFA)

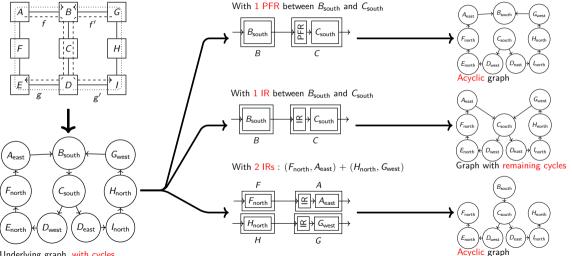
- Delay bound in a node
- Fixed-point
- FP-TFA overview

3 Analysis

- A parametric topology
- Industrial case

Modeling the effect of regulators on cyclic dependencies

Network, with cyclic dependencies

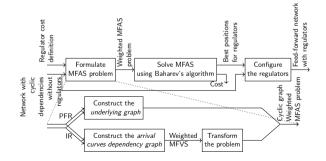


Underlying graph, with cycles

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Obtaining minimum positions

- With PFRs: Minimum Feedback Arc Set (MFAS)
- With IRs: Minimum Feedback Vertex Set (MFVS)
- Both are equivalents.
- Solved using a state-of-the-art optimal algorithm [Baharev et al., 2015].



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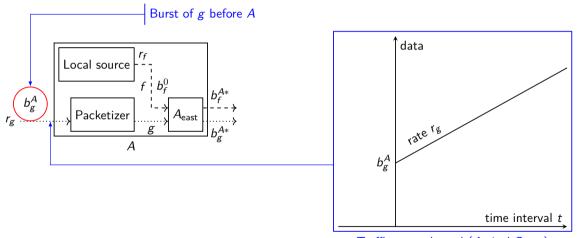
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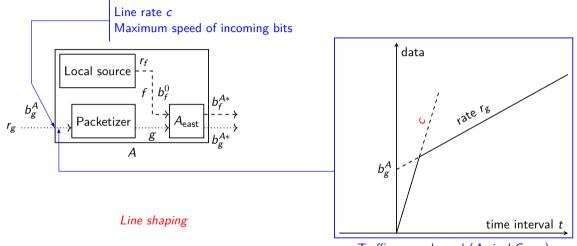
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Example:



Traffic upper-bound (Arrival Curve)

Example:

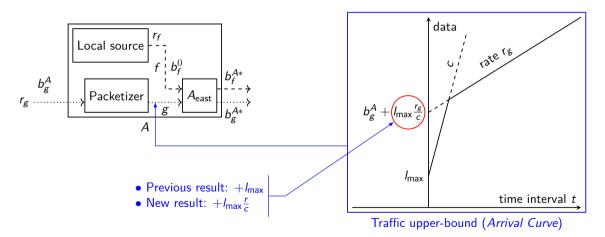


Traffic upper-bound (Arrival Curve)

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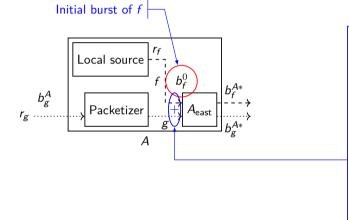
Fixed-Point Total Flow Analysis (FP-TFA) Delay bound in a node

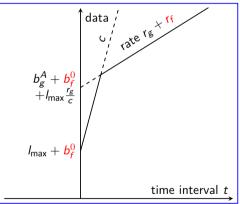
Example:



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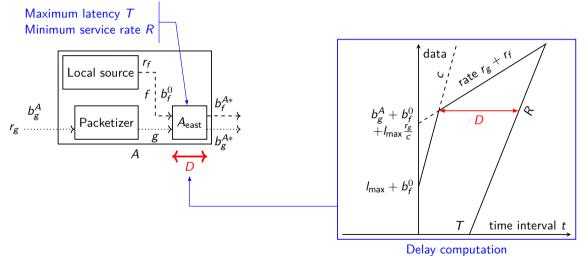
Example:





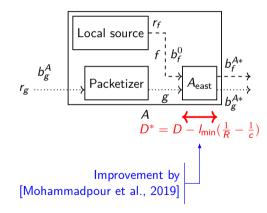
Traffic upper-bound (Arrival Curve)

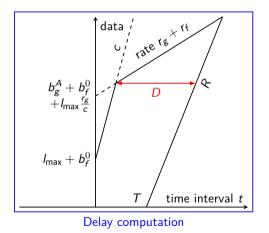
Example:

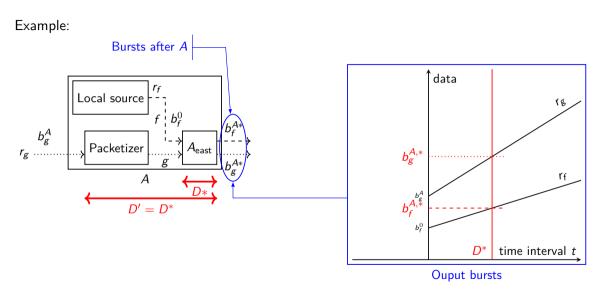


Fixed-Point Total Flow Analysis (FP-TFA) Delay bound in a node

Example:

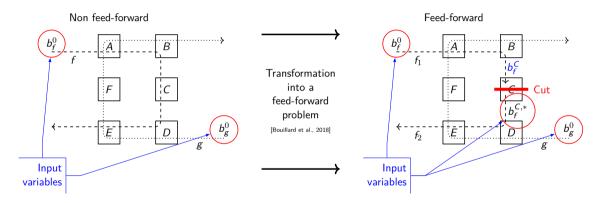






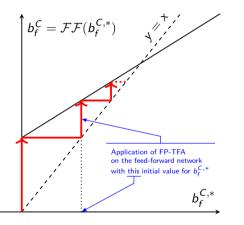
Fixed-point

Networks with cyclic dependencies

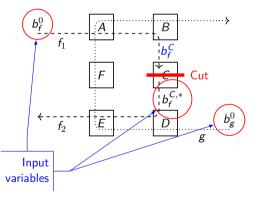


Fixed-point

Networks with cyclic dependencies



Feed-forward



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Fixed-point

Improved result on the fixed-point

Time-stopping proof, in [Bouillard et al., 2018]

The **highest** fixed-point of \mathcal{FF} is a valid burst bound at the cuts.

In our paper

If the network is empty at t = 0, then any fixed-point of \mathcal{FF} is a valid burst bound at the cuts.

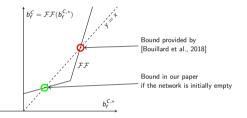
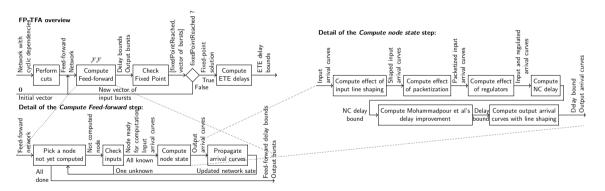


Figure: Schematic representation of \mathcal{FF} with several fixed-points

FP-TFA algorithm



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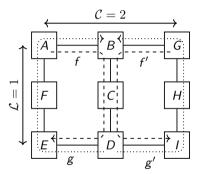
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A parametric grid topology

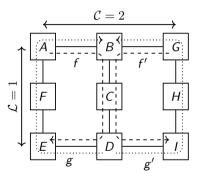
Symmetries (G, I), $(E, I) \rightarrow$ control of the network size.



Number of placed regulators

Partial deployments with LCAN require $81\%^1$ to $89\%^2$ fewer regulators than the **total**-deployment scheme.

Cyclic dependencies can be removed from this network with very few regulators.



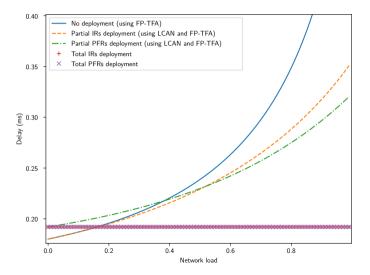
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¹When using Interleaved Regulators (IRs) ²When using Per-Flow Regulators (PFRs)

Latency bounds with respect to network load

Figure: End-to-end delay bound of the flows on the grid versus the network utilization.

- Full-deployment: penalty at low load compared to no deployment, but benefit at high load.
- Partial deployment: never the best performance but good compromise.

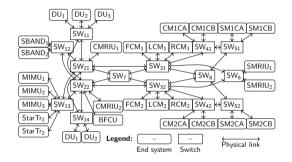


A representative industrial case

Orion spacecraft [Obermaisser, 2011, Zhao et al., 2018]. 119 arbitrary multicast high-priority flows >293'000 cyclic dependencies.

- Total deployment: 249 regulators.
- Partial deployment: 14 IRs or 9 PFRs.

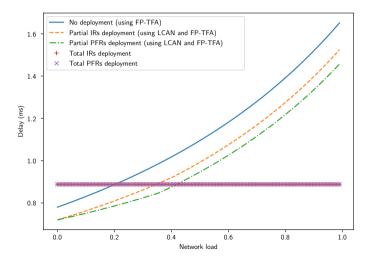
Substantial cost savings can be achieved in industrial cases.



Performance evaluation on the industrial case

Figure: Highest ETE delay bound of the flows within Orion versus the network load.

- No-deployment scheme no longer the best approach at low load.
- Benefit of regulators (even partially) in heterogeneous networks.



Conclusion

- **FP-TFA** computes **latency bounds** in networks **with** *cyclic dependencies*.
- LCAN removes the cyclic dependencies using traffic shaping, with the minimum number of PFRs/IRs.
- Analysis on parametric/industrial topologies:
 - Low load \Rightarrow significant effect of *line shaping*.
 - At medium to large load \Rightarrow benefit of regulators becomes apparent.
 - Partial deployment of Per-Flow Regulators (PFRs) offers a good compromise between performances and deployment cost.
 - Interleaved regulators (IRs) need to be placed everywhere to provide noticeable improvement.

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